



# Testing of an F/A-18 Automatic Carrier Landing System Using Shipboard Relative GPS



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# Overview



- ◆ JPALS Program
- ◆ System Description
- ◆ Development and Build-Up Testing
- ◆ Shipboard Testing
- ◆ Flight Test Results



# Joint Precision Approach and Landing System (JPALS)



## Ground Systems

### Civil/International



Civil C/A-Code

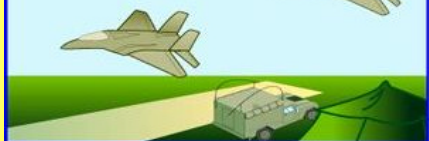
### Fixed Base



Military  
P(Y)-Code  
GPS



### Tactical/Spec Msn



P(Y)- Code  
Anti-Jam  
Portable



### Shipboard



P(Y) Code  
Kinematics  
Anti-Jam



VHF

VHF

VHF

UHF

### Antenna



### GPS



### Data Link



### Display



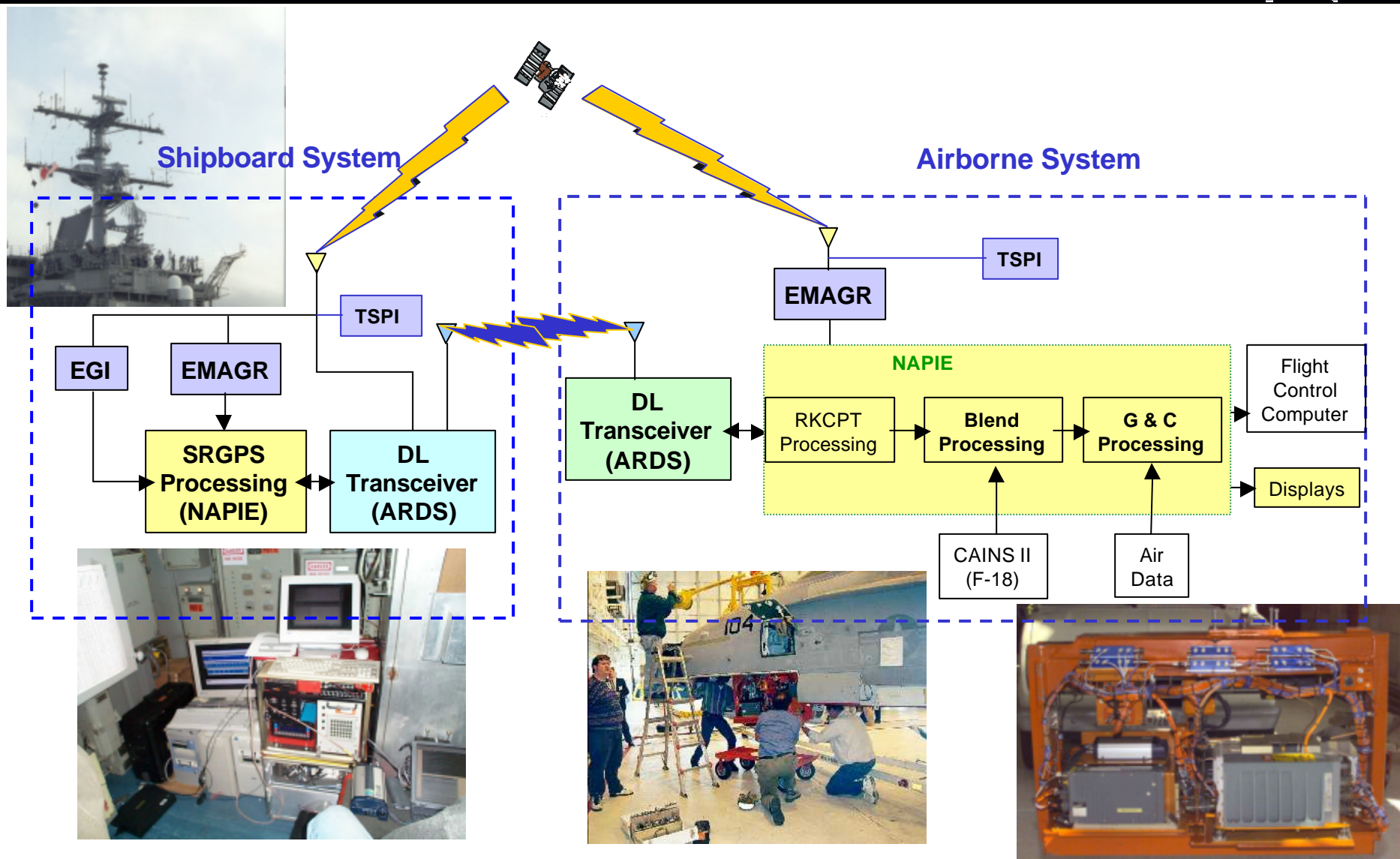
### Mission Computer

## Airborne Equipment





# SRGPS Hardware Diagram







# Naval Avionics Platform Integration Emulator (NAPIE)



- ◆ Allows production aircraft to be used as a flying avionics test bed with minimal modifications and without changes to aircraft operational flight programs (OFP) or avionics
- ◆ Use existing aircraft systems and displays where possible
- ◆ System can be isolated from the aircraft via bus relays (Isolate/Operate Switch)



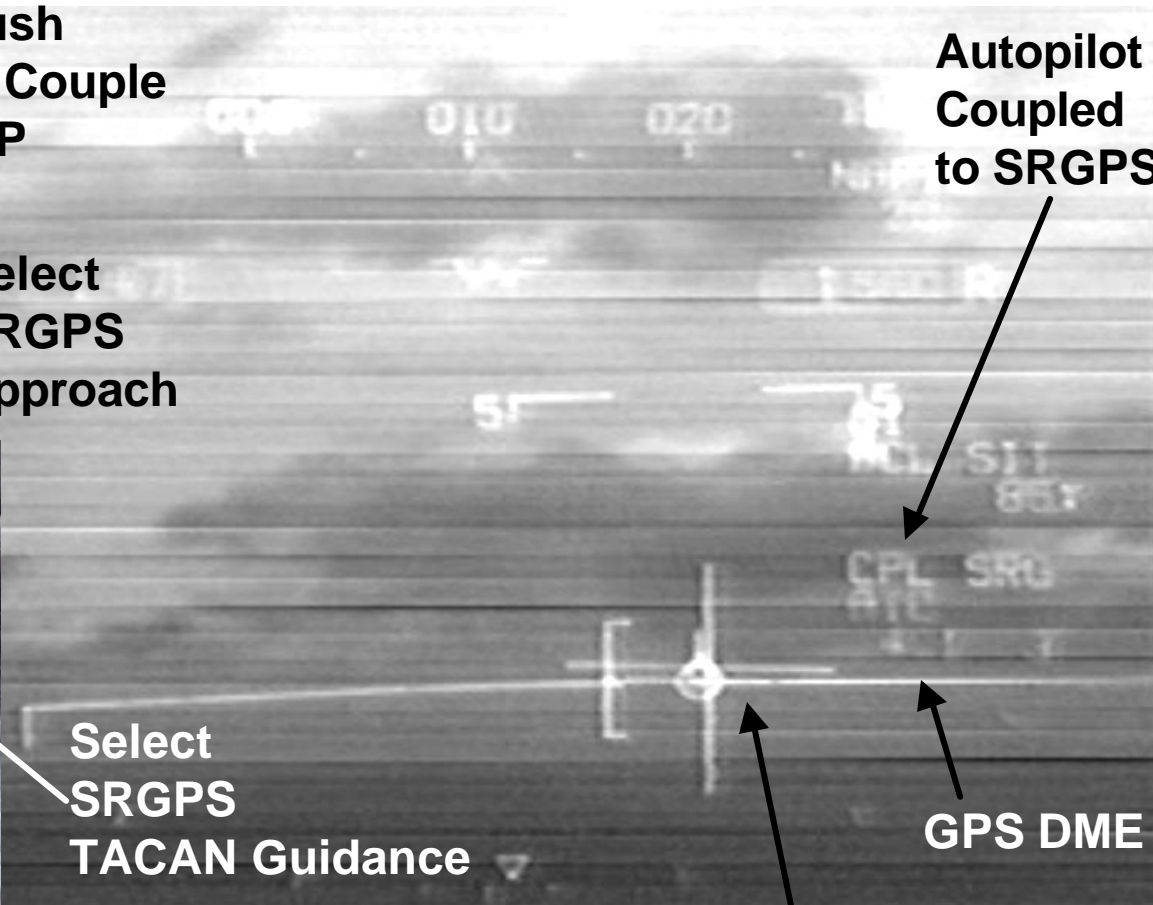


# Push to Couple A/P

## Select SRGPS Approach



## Select SRGPS TACAN Guidance



## Autopilot Coupled to SRGPS

## GPS DME

## Guidance Display



# Key Test Tools Used



- ◆ Ability to replay collected raw sensor data through algorithms (For System Optimization)
- ◆ Quick upload of new software (incl. NAPIE Display Changes)
- ◆ Real-time download of critical performance parameters
- ◆ Quick Look Data Reports
  - ◆ Sensor
  - ◆ KCPT
  - ◆ Guidance and Control
  - ◆ Time Space Position Information (TSPI)





# Van Testing



- ◆ Van testing was used to verify system design between two moving platforms
- ◆ Benefits:
  - ◆ Van was more available and accessible than the aircraft
  - ◆ Build confidence in system design prior to aircraft integration
  - ◆ Risk mitigation
  - ◆ Significant cost savings in preliminary testing





# On Aircraft Ground Testing



- ◆ Ground testing using actual aircraft and system hardware allowed for quick verification of changes made during development
- ◆ Use of a GPS simulator allowed repeatable controlled scenarios
- ◆ Testing in the hangar allowed for rapid development regardless of weather





# Shore Based Build-Up Testing



- ◆ Build-up confidence in system performance prior to shipboard testing
- ◆ Final stages of system development and performance optimization



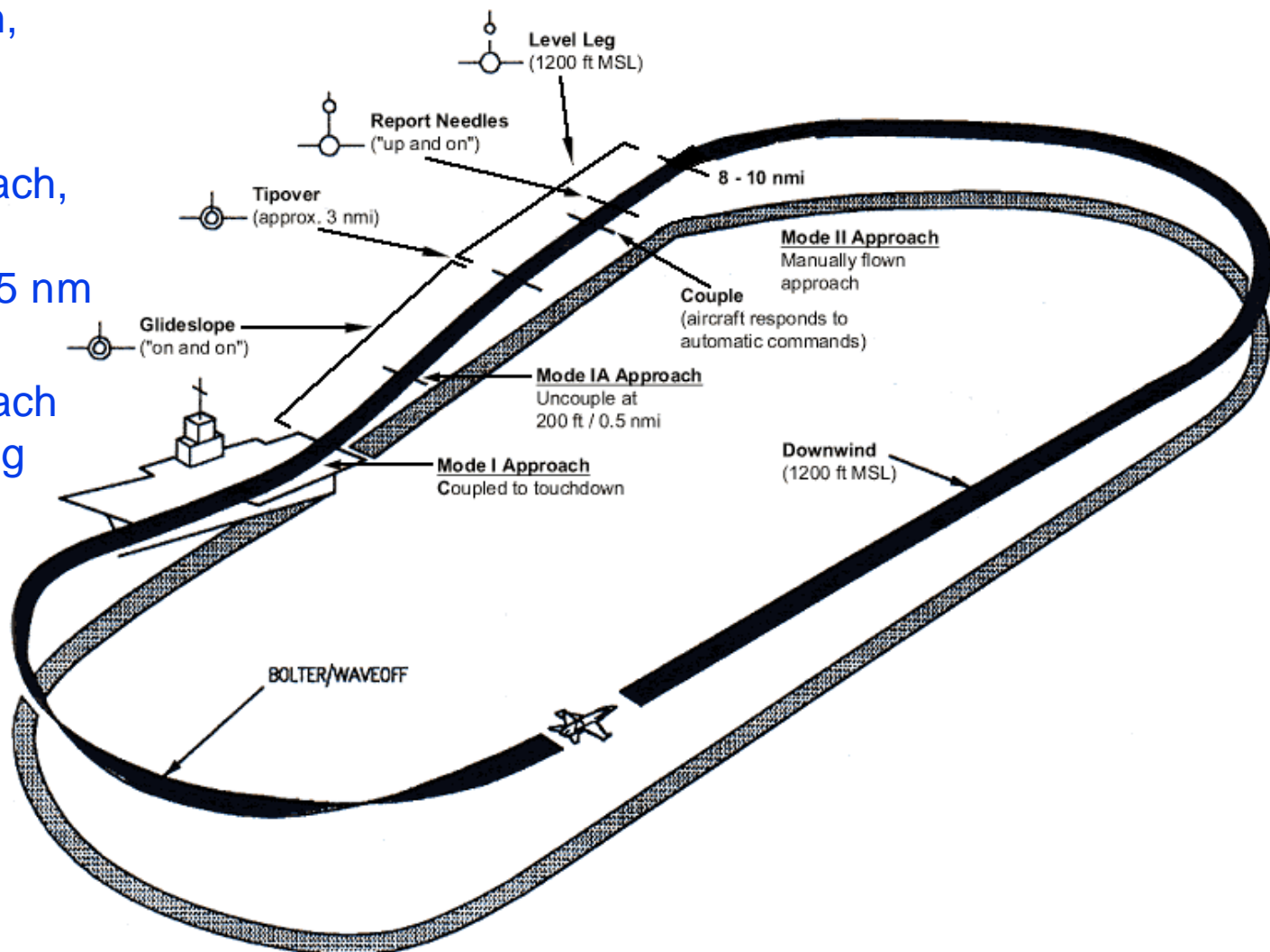


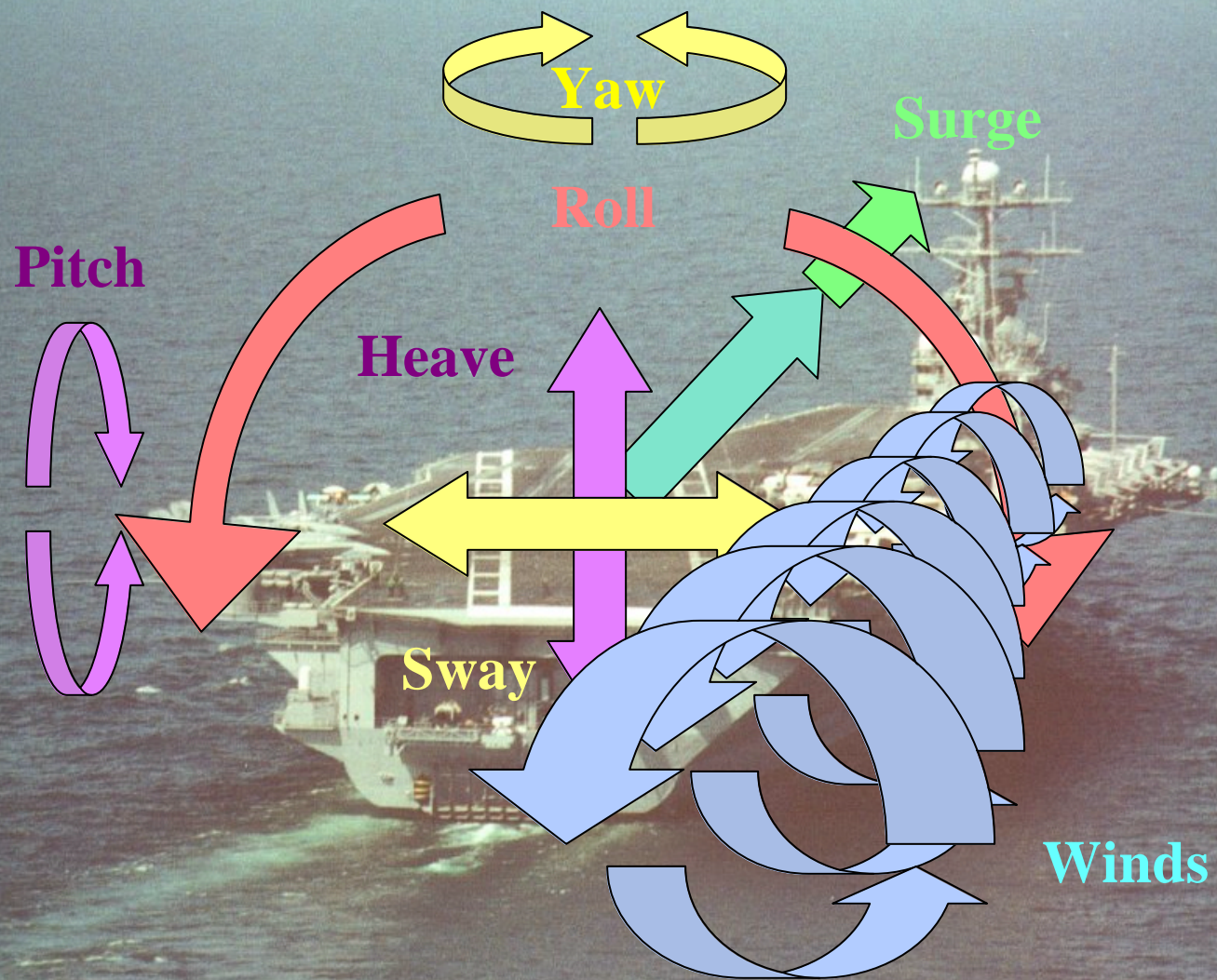


# Shipboard Approaches



- ◆ Manual Approach, Manual Landing (Mode II)
- ◆ Automatic Approach, Manual Landing from 200ft and 0.5 nm (Mode IA)
- ◆ Automatic Approach Automatic Landing (Mode I)



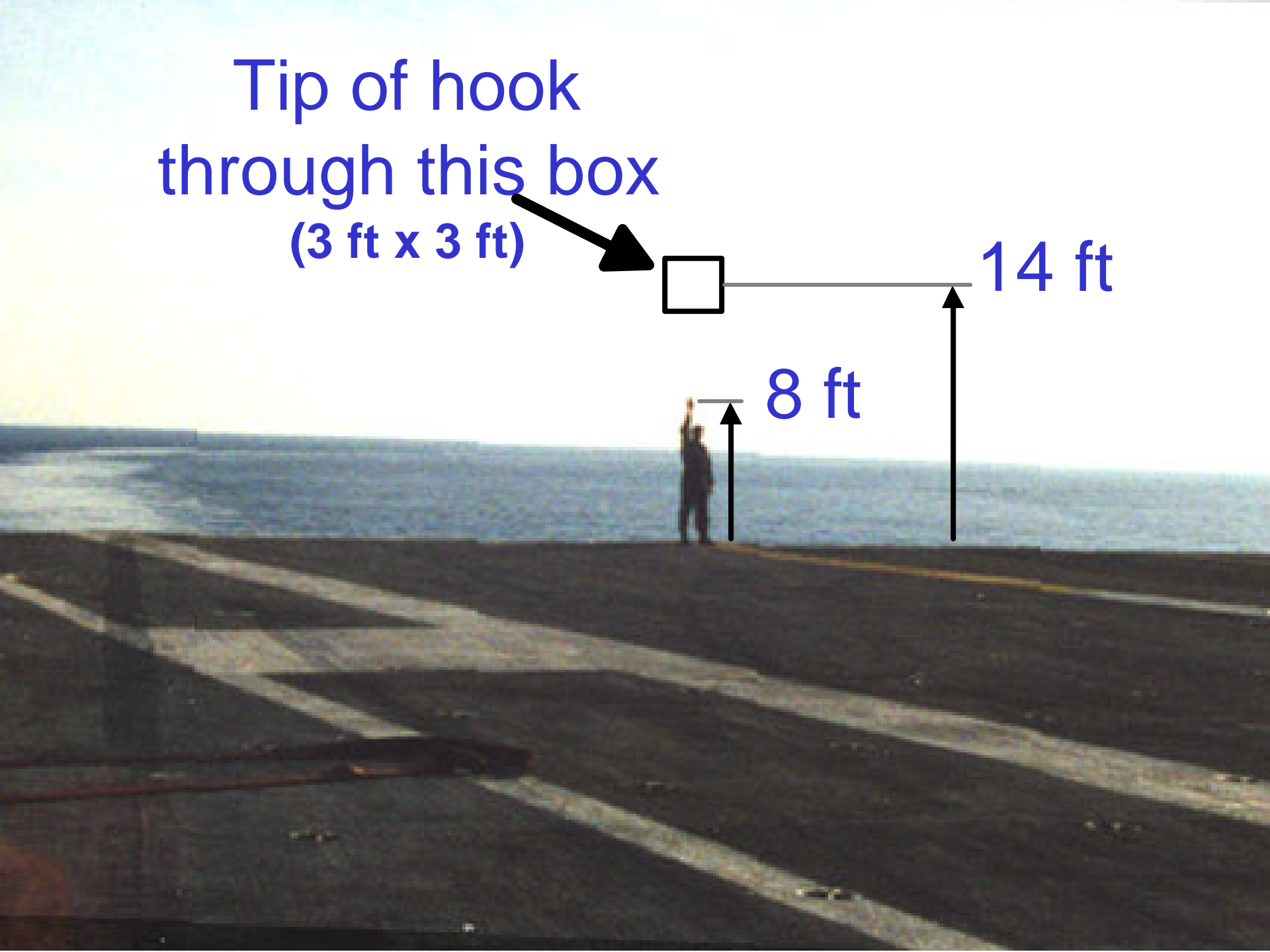


Tip of hook  
through this box  
(3 ft x 3 ft)



14 ft

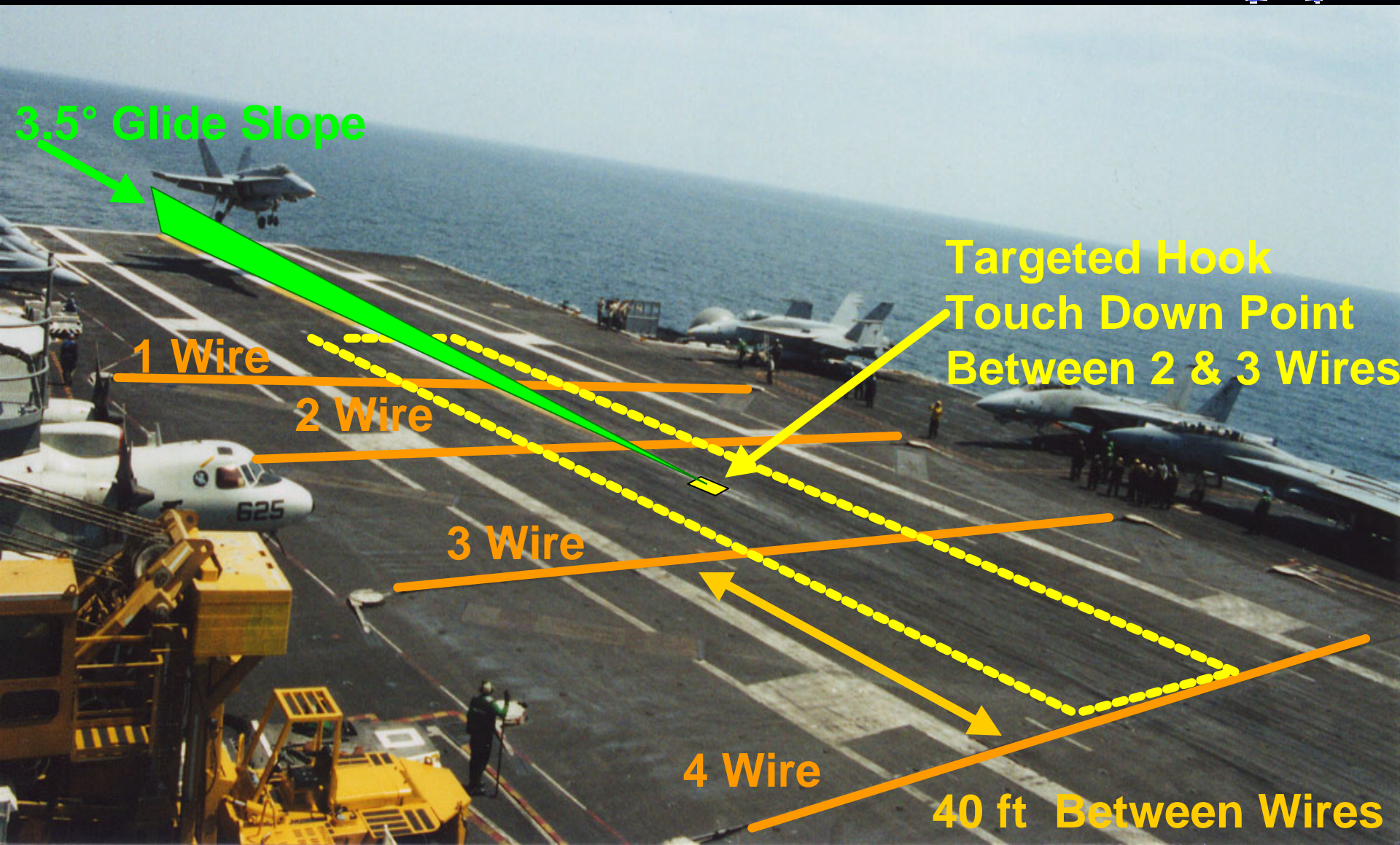
8 ft







# Carrier Deck Landing Area







# Shipboard Installation



Shipboard System (SPN-43 rm)



Real Time Display  
(SPN-46 rm)

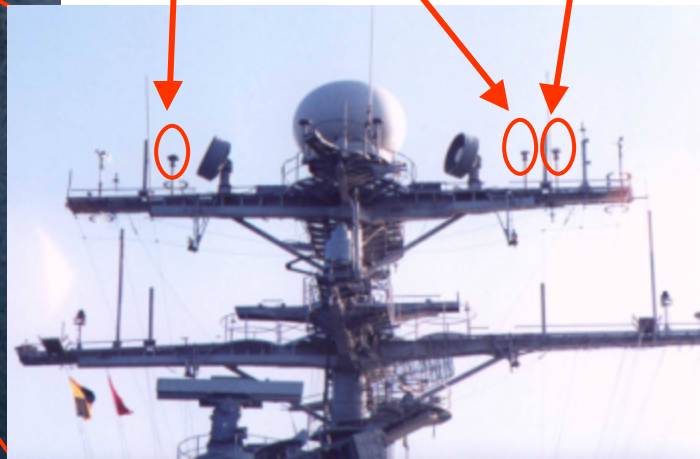
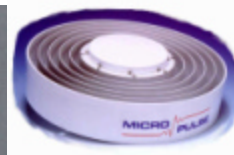
## Yardarm FRPA Antennas

- 1) Starboard - Shipboard FRPA
- 2) Inner Port - FRPA
- 3) Outer Port - Choke Ring FRPA

1)

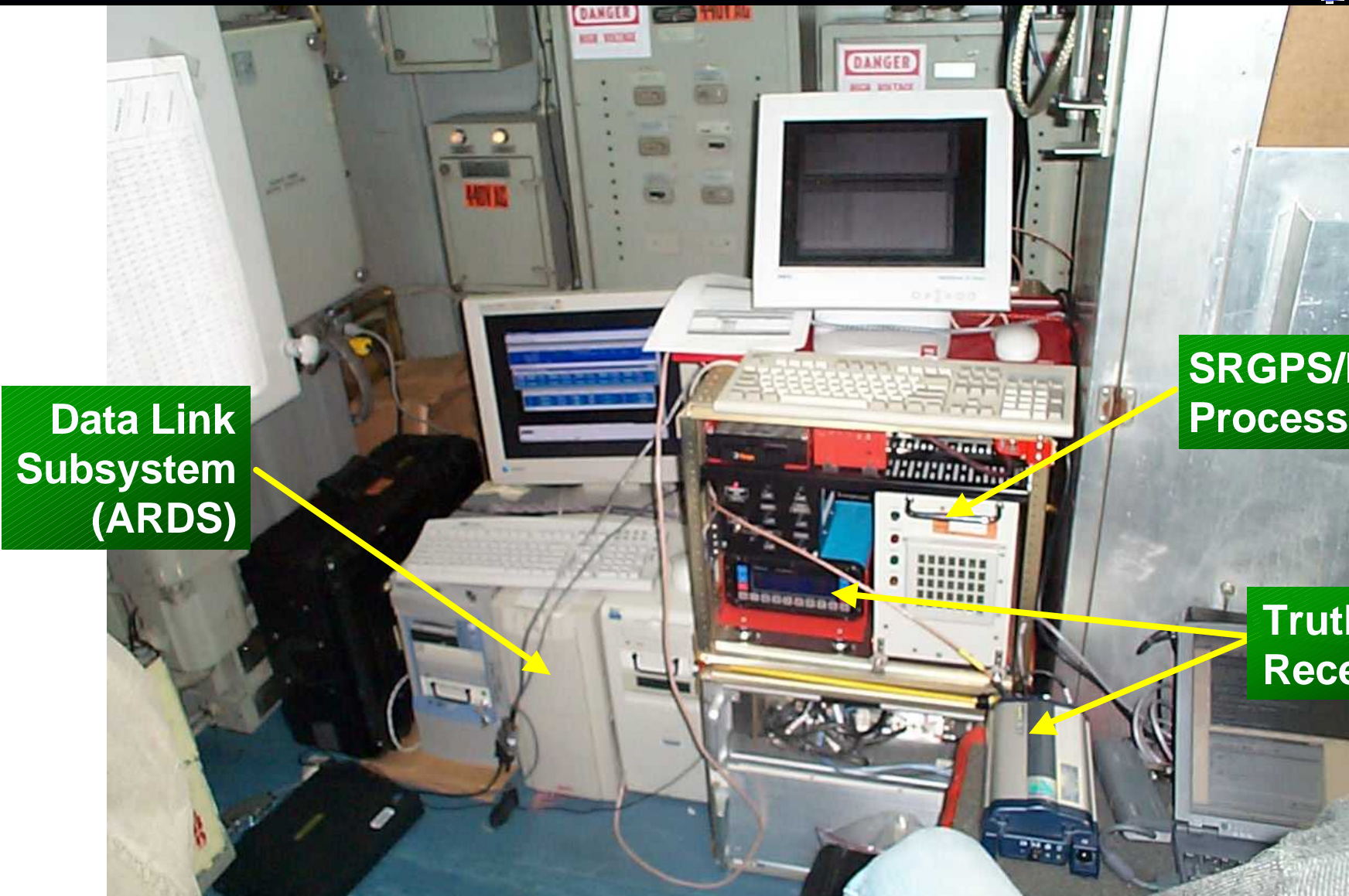
2)

3)





# Shipboard System



**Data Link  
Subsystem  
(ARDS)**

**SRGPS/NAPIE  
Processor**

**Truth  
Receivers**





# Shipboard Flight Testing USS. Theodore Roosevelt



- ◆ Shipboard Flight Testing April 20 - 24, 2001
  - ◆ 10 Mode I's (Auto Landing)
  - ◆ 24 Elevated TDP Mode I's and IA's (100-400 ft)
  - ◆ 6 Mode II's (Manual Control)
- ◆ Total of 6.6 hours of Shipboard Flight Testing
- ◆ Demonstrated feasibility of SRGPS in the shipboard operational environment

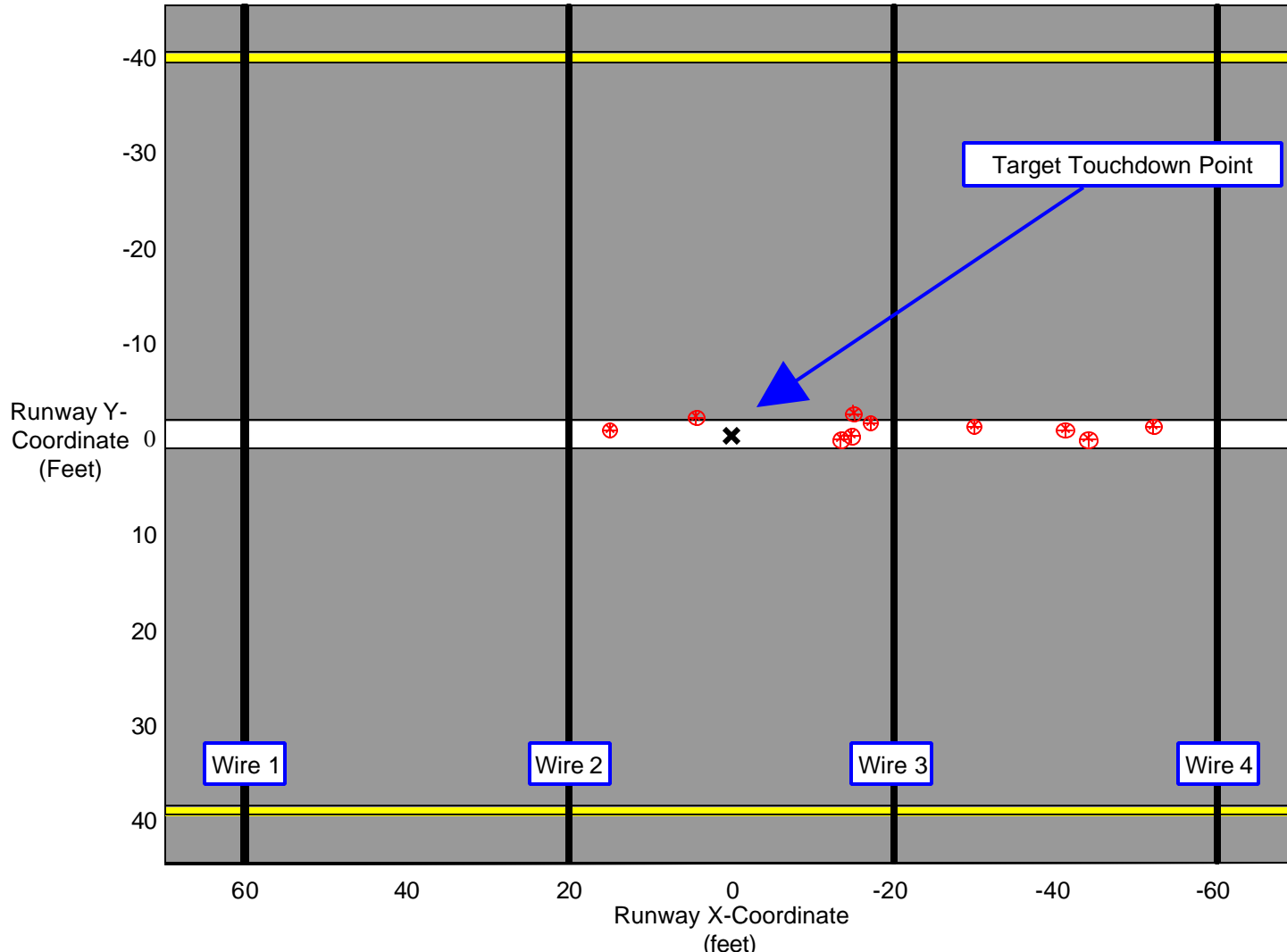




# Visual View of Hook Touchdown



Touchdown Points - Coupled to the Deck  
April 23-24, 2001 - USS Theodore Roosevelt (CVN-





# Questions?

